
Oral presentation | Fluid-structure interaction

Fluid-structure interaction-I

Mon. Jul 15, 2024 10:45 AM - 12:45 PM Room A

[1-A-04] Numerical investigation of correlation between thrust and angle of attack in a cyclorotor system

*Manabu Saito¹, Jun Nagao¹, Ryoichi Kurose¹ (1. Kyoto University)

Keywords: Cyclorotor, Large-eddy simulation, Propulsion system



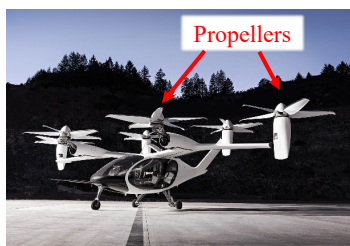
Numerical investigation of correlation between thrust and angle of attack in a cyclorotor system

Manabu Saito, Jun Nagao, Ryoichi Kurose

Thermal Science and Engineering Laboratory
Dept. of Mechanical Engineering and Science
Kyoto University

1

Background

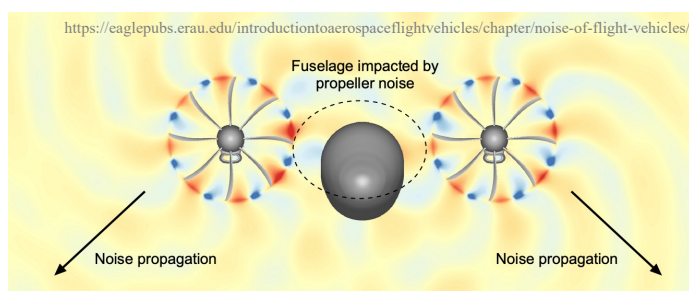


S4 ©Joby Aviation



VX4 ©Vertical Aerospace

For Urban Air Mobility (UAM), Vertical Take-Off and Landing (VTOL) aircraft is considered.



Propellers are used as a propulsion system

→ Intense noise generation has been the biggest problem



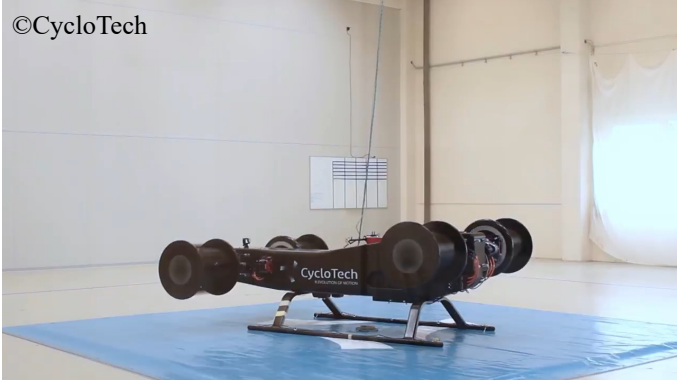
To overcome the noise problem in UAM, "Cyclorotor" is gaining attention as an alternative propulsion system

ICCFD12

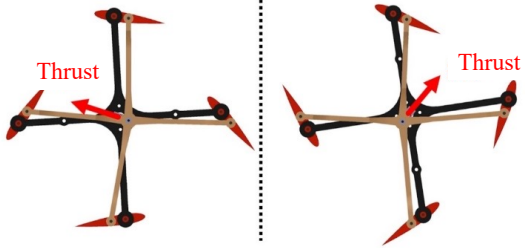
2

Cyclorotor

©CycloTech



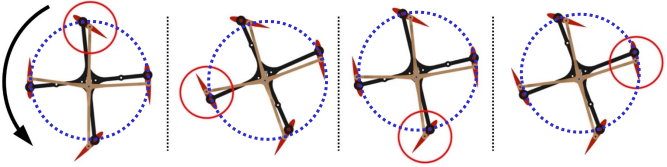
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360° thrust vectoring

Main features of a Cyclorotor:

- **Maneuverability** - Thrust in any direction/magnitude
- **Lower noise level** - Lower blade-tip speed

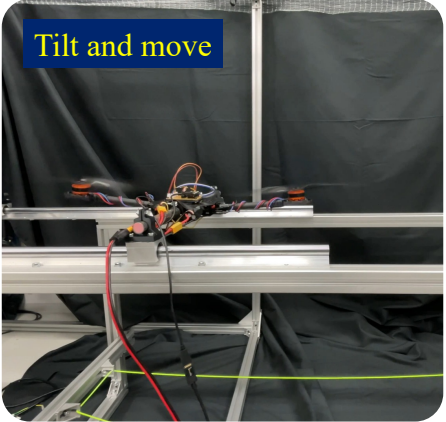


3

Flight capability of cyclorotor-powered aircraft

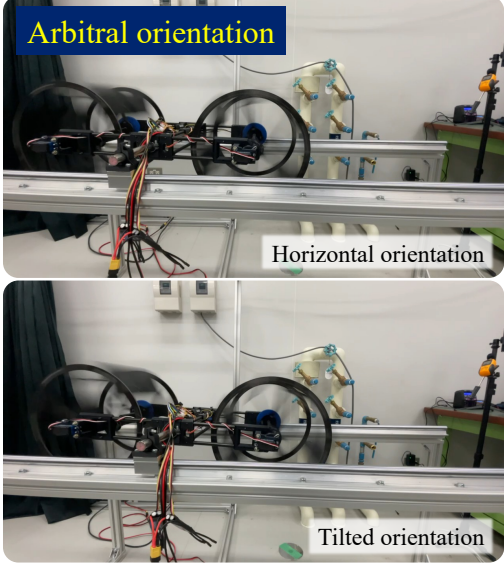
Propeller

Tilt and move



Cyclorotor

Arbitral orientation



Horizontal orientation

Tilted orientation

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4

Flight stability against sidewind

Propeller

Weak wind
6 m/s

Unstable

Cyclorotor

Stable

Propeller

Strong wind
11 m/s

Flips over

Cyclorotor

Stable

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5

Geometrical optimization of a cyclorotor


Optimization properties:

- Number of blades
- Airfoil shape (cross section/taper angle)
- Rotational radius
- Span length
- Angle of attack schedule
- ...

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6

Geometrical optimization of a cyclorotor



Optimization properties:

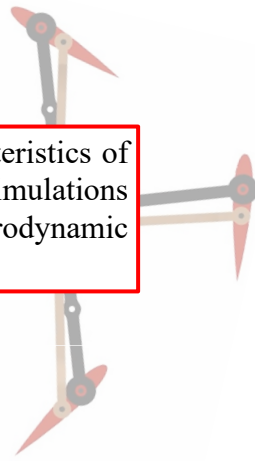
- Number of blades

To conduct an in-depth study of the aerodynamic characteristics of the airflow produced by cyclorotors using large-eddy simulations and find an optimal AoA schedule to maximize the aerodynamic performance of a cyclorotor.

- Span length

- Angle of attack schedule


...




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7

Computational domain





NACA0010

Cyclorotor[4]

Shape
NACA0010

Span length
150 mm

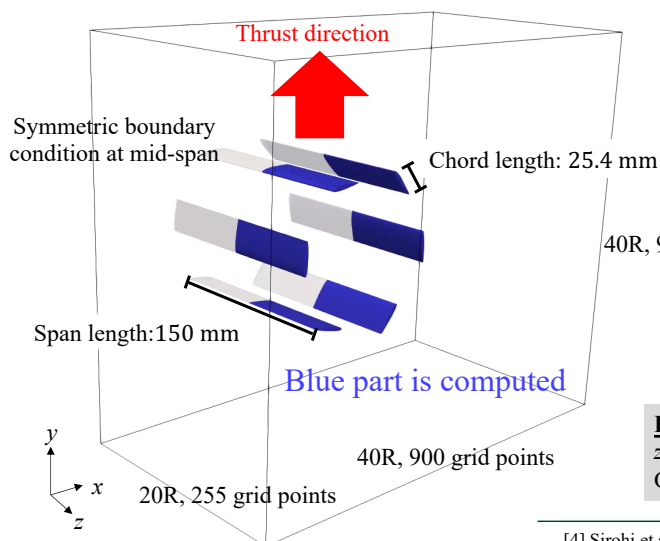
Chord length
25.4 mm

Radius (R)
60 mm

Rotational speed (Ω)
800 rpm

Reynolds number
10,000

Angle of attack
-20° ~ 20°



Initial condition
Static air
Pressure: 1 atm
Temperature: 300 K

Boundary condition
z-direction (-): Symmetric
Others : Outflow

40R, 940 grid points

40R, 900 grid points

20R, 255 grid points

Span length: 150 mm

Chord length: 25.4 mm

Symmetric boundary condition at mid-span

Blue part is computed

[4] Sirohi et al., *J. Am. Helicopter Soc.*, 2007

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8

Computational method

150 mm
120 mm
Minimum grid size:
 $(\Delta x^+, \Delta y^+, \Delta z^+) = (7, 7, 7)$
Smaller grid size towards blade tip

25.4 mm

Eulerian Point
Lagrangian Point
Ω
Γ
Immersed boundary method

- Incompressible N-S equations, Finite difference method (FVM)
- Number of grid points: $(n_x, n_y, n_z) = (900, 940, 255)$ (total of 0.2 billion)
- Wall surface: Diffuse-interface immersed boundary method (IBM) (Boundary-condition enforced IBM) [5]
- Number of Lagrangian points for each blade: 28,141

[5] Pinelli et al., *J. Comput. Phys.*, 2010

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9

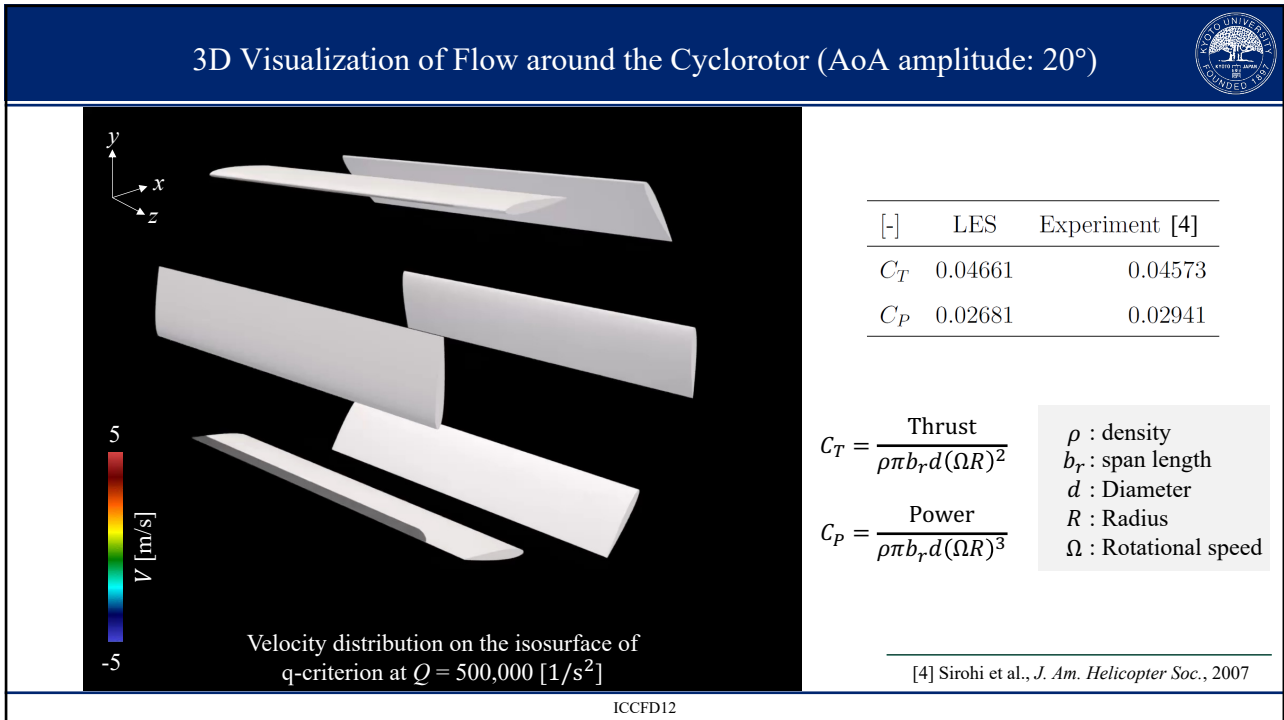
Angle of attack schedule

90°
120°
60°
150°
25.4 mm
NACA0010
Diameter: 120 mm
180°
210°
30°
0°
240°
270°
300°
330°
Azimuthal angle

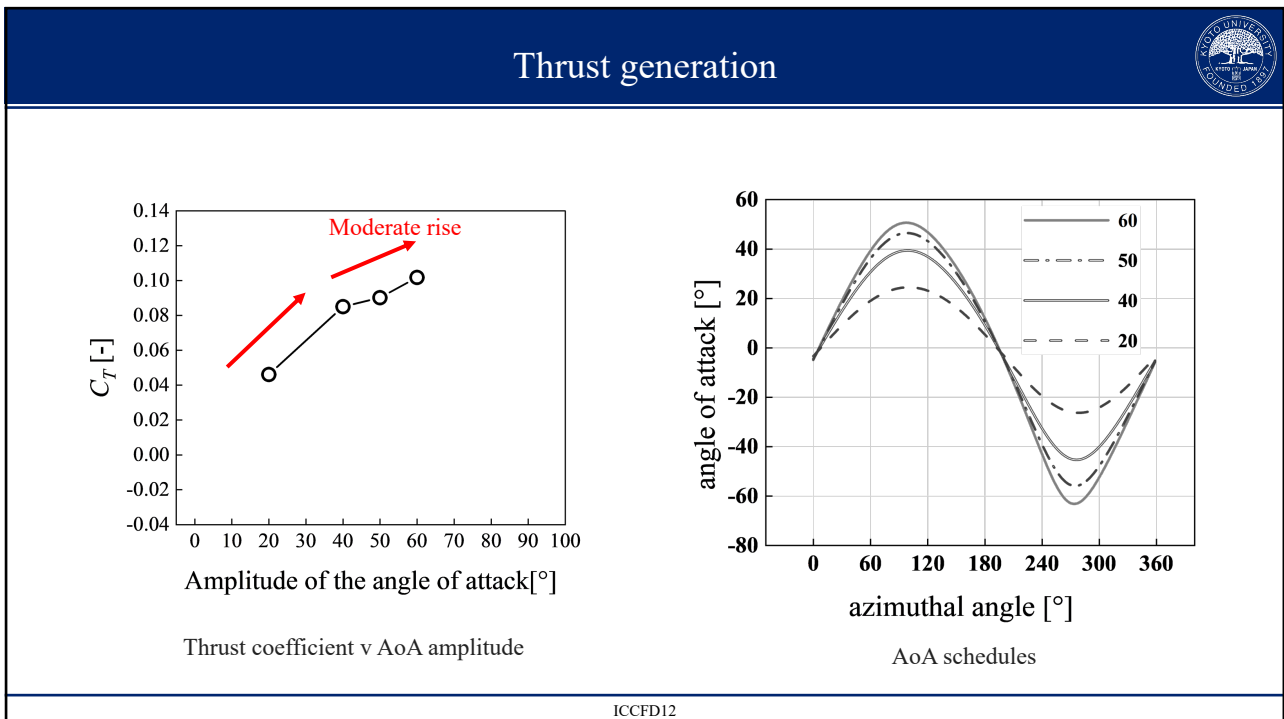
angle of attack [°]
azimuthal angle [°]

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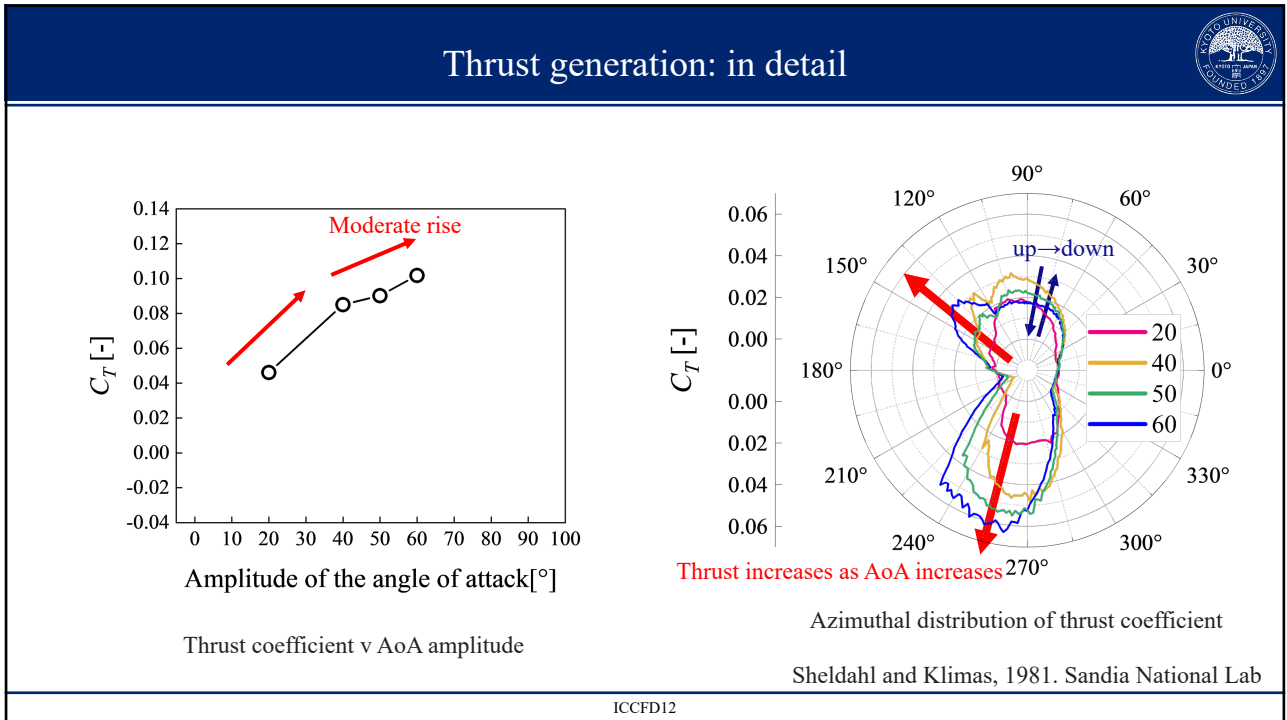
10



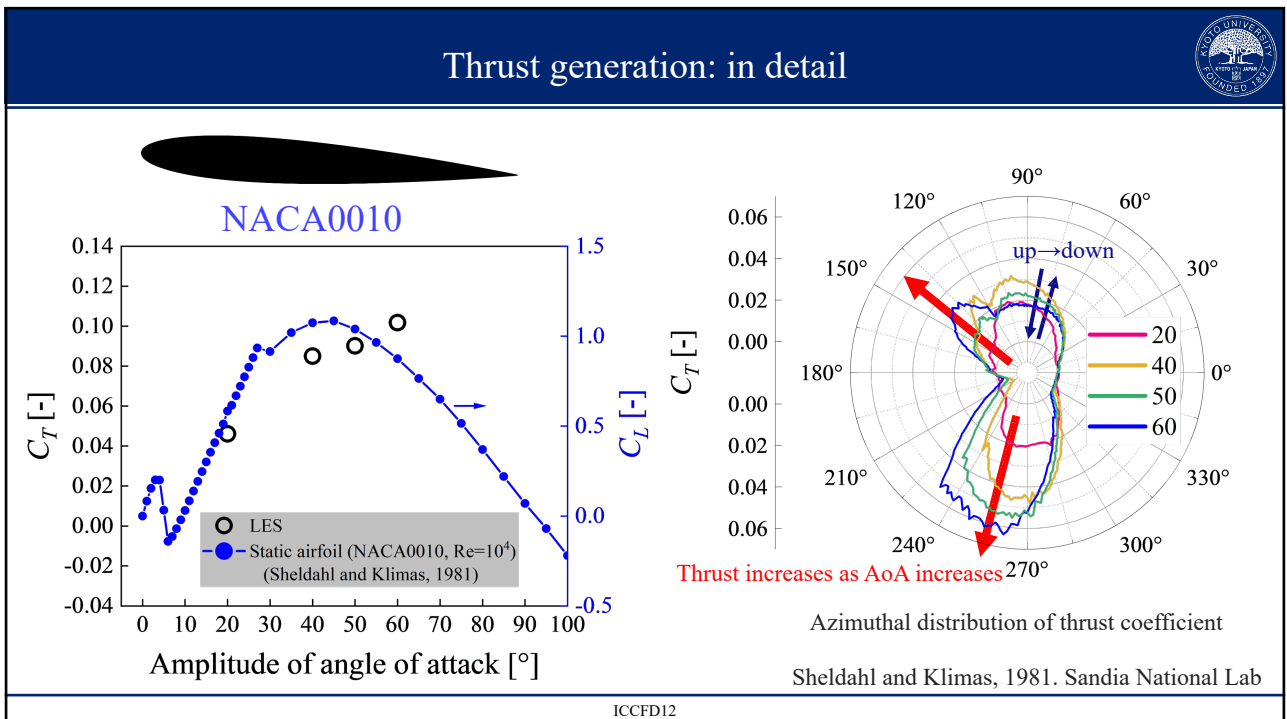
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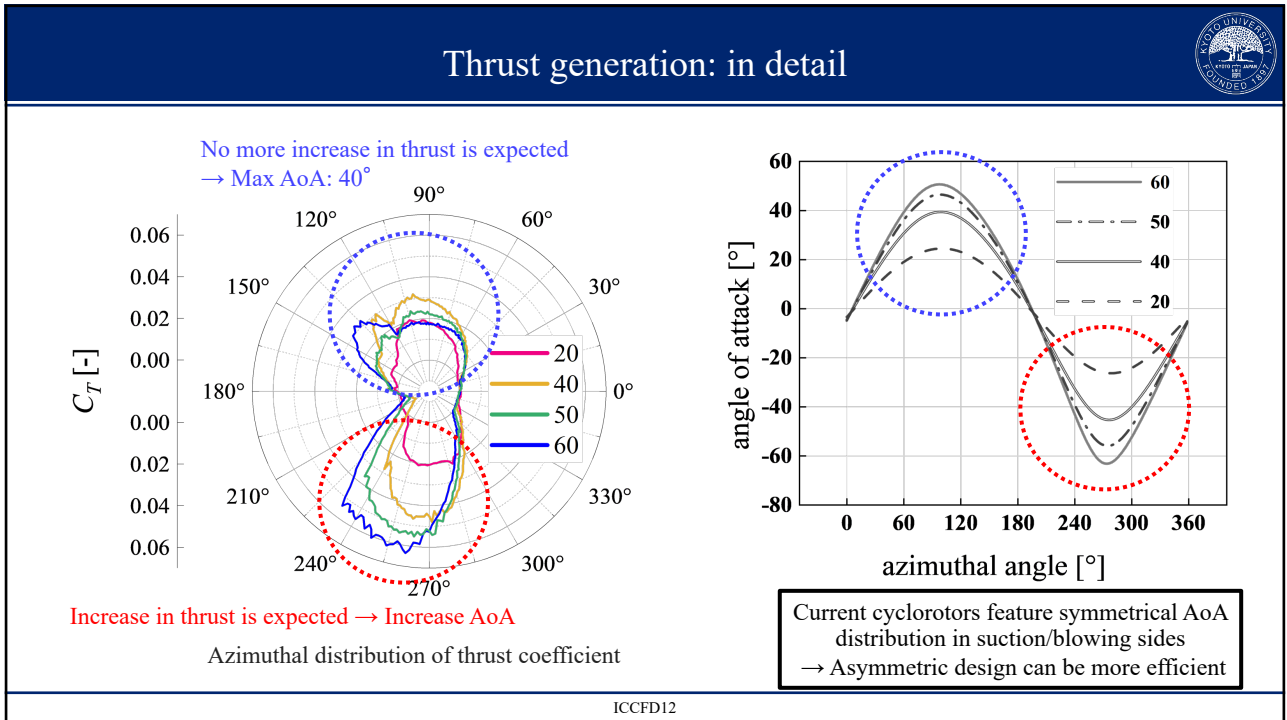
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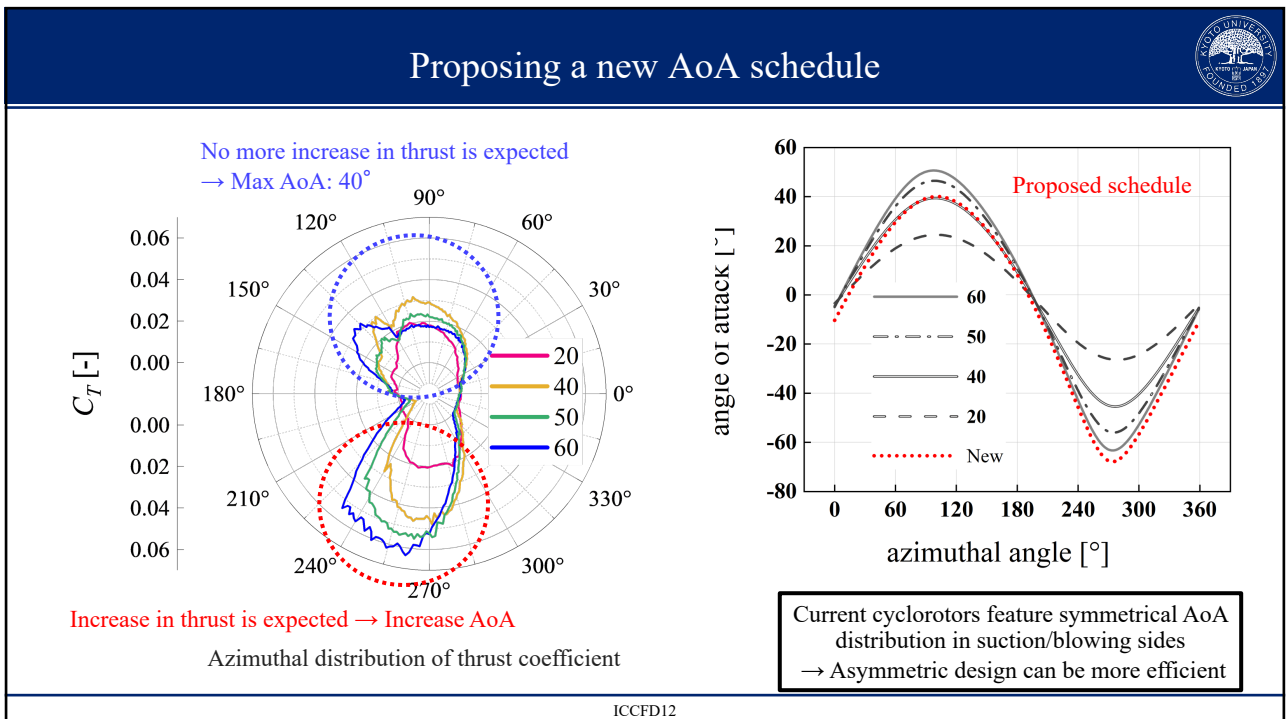
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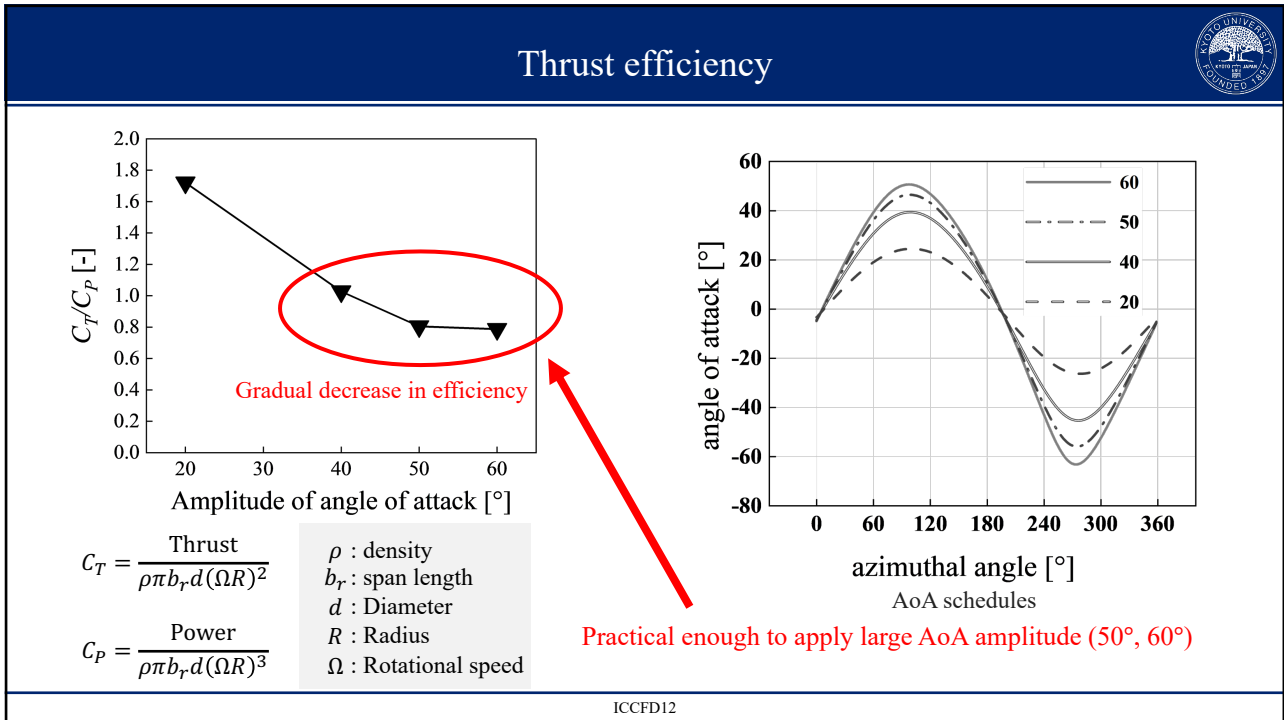
14



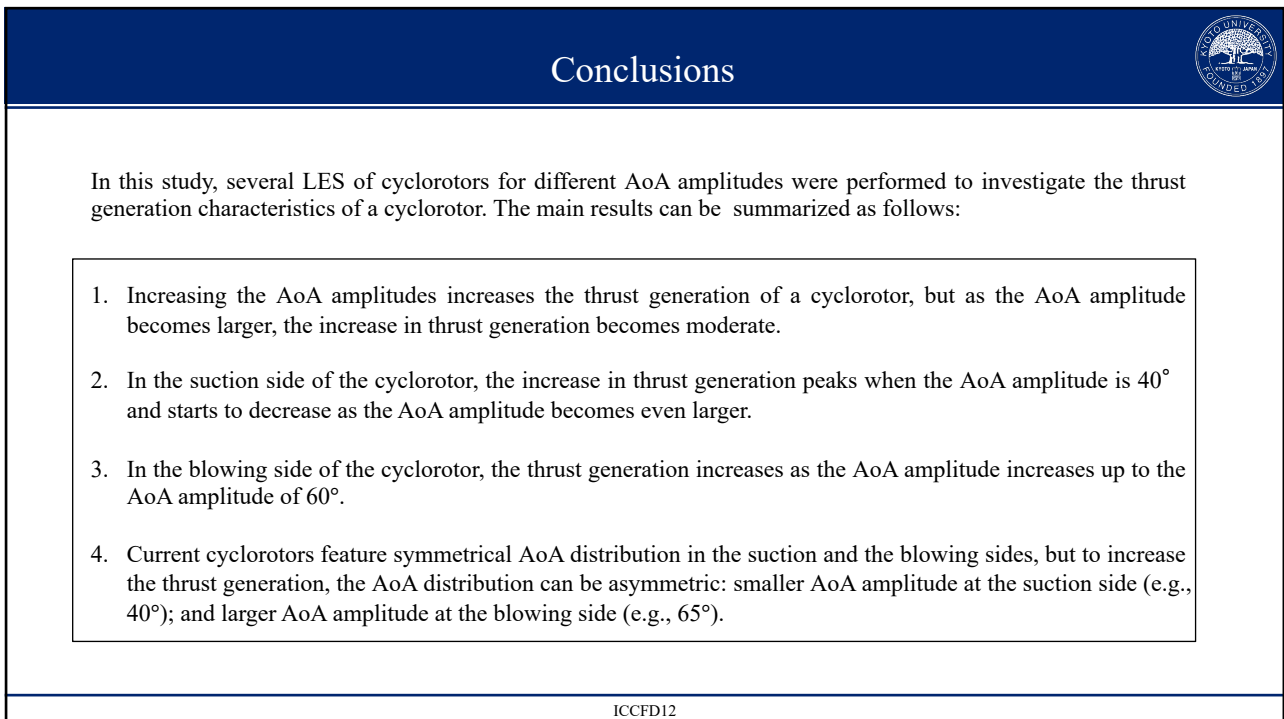
15



16



17



18